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### Quantum Advantage

#### Article

# Quantum supremacy using a programmable superconducting processor

https://doi.org/10.1038/s41586-019-1666-5 Received: 22 July 2019 Accepted: 20 September 2019 Published online: 23 October 2019

Bapel Hanes," Sergin Book, Ternetoki G. S. L. Bandes," Social A. Buell, Beine Basterl, V. Lover, "Electronic Basel Carlo," Indext Conf. 2016. IEEE Conf. 2016, IEEE Conf. 201

Frank Arute', Kunal Arya', Ryan Babbush', Dave Bacon', Joseph C. Bardin'<sup>2</sup>, Rami Barends',

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#### RESEARCH

#### QUANTUM COMPUTING

#### Quantum computational advantage using photons

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#### Strong quantum computational advantage using a superconducting quantum processor

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#### Google, 2019.

USTC, 2021.

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#### Quantum advantage but classically intractable to verify results.

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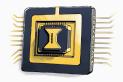
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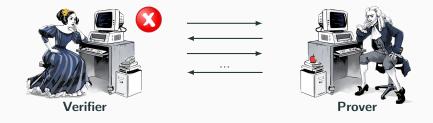




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Let  $\lambda \in \mathbb{N}$  be a security parameter. A PoQ is an interactive protocol between a  $poly(\lambda)$ -time *classical verifier* and a  $poly(\lambda)$ -time prover, such that

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Soundness is based on a computational assumption.

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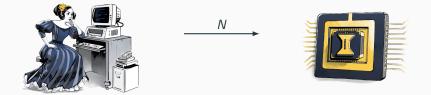




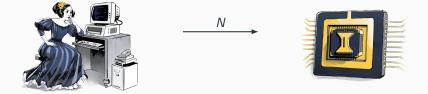




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Can construct such PoQs from any problem, P, such that<sup>1</sup>  $P \in \mathsf{BQP}, \ P \notin \mathsf{BPP}.$ 

<sup>1</sup>Technically, want  $P \notin AVBPP$ .

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#### Trapdoor claw-free function (TCF)

We say a family  $\{f_{\lambda} : \mathcal{I} \to \mathcal{O}\}_{\lambda \in \mathbb{N}}$  is a TCF family if:

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Poly-time algorithm that, given  $x \in \mathcal{I}$ , computes  $f_{\lambda}(x)$ .

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For every  $y \in Im(f_{\lambda})$ , there are exactly two  $x_0, x_1 \in \mathcal{I}$ ,  $f_{\lambda}(x_0) = f_{\lambda}(x_1) = y$ .

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#### Trapdoor

There is a trapdoor  $t_{\lambda}$  and a poly-time algorithm that, given  $t_{\lambda}$  and  $y \in Im(f_{\lambda})$ can compute  $x_0, x_1 \in \mathcal{I}$ , such that  $f_{\lambda}(x_0) = f_{\lambda}(x_1) = y$ .

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#### PoQs with more than 2 messages

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STCFs can be constructed from LWE.

TCFs can be constructed from factoring, discrete-log, Ring-LWE, LWE.





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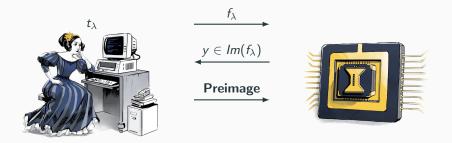
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$$y \in Im(f_{\lambda})$$



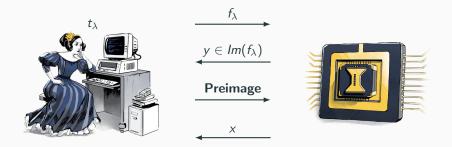
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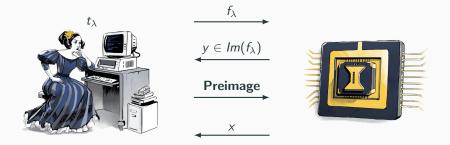
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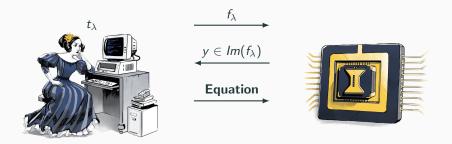
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Verifier accepts if  $f_{\lambda}(x) = y$ .

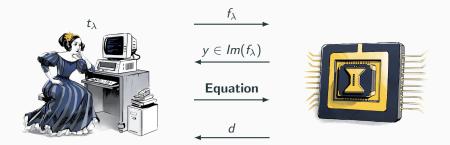
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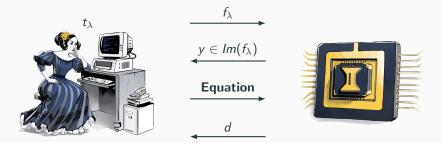


Verifier accepts if  $d \cdot (x_0 \oplus x_1) = 0$ , with  $f_{\lambda}(x_0) = f_{\lambda}(x_1) = y$ .

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Verifier uses  $t_{\lambda}$  to obtain  $x_0$ ,  $x_1$  from y and checks the equation.



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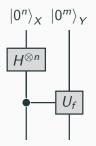
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 $|0^{n}\rangle_{X} |0^{m}\rangle_{Y}$ 



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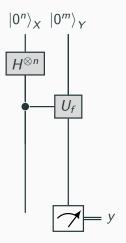
$$\frac{1}{\sqrt{2^n}}\sum_{x\in\{0,1\}^n}|x\rangle_X \quad |0^m\rangle_Y$$



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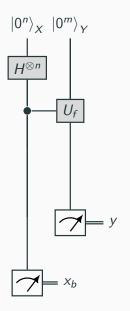


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$$\frac{1}{\sqrt{2}}(|x_0\rangle+|x_1\rangle)_X |y\rangle_Y$$



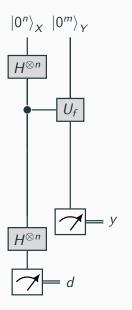
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angle_Y$ 

$$rac{1}{\sqrt{2^n}}\sum_{x\in\{0,1\}^n}|x
angle_X \quad |f_\lambda(x)
angle_Y$$

$$\frac{1}{\sqrt{2}}(|x_0\rangle + |x_1\rangle)_X |y\rangle_Y$$

**Preimage case**:  $x_b$ ,  $b \leftarrow_U \{0, 1\}$ 



$$|0^n\rangle_X |0^m\rangle_Y$$

$$rac{1}{\sqrt{2^n}}\sum_{x\in\{0,1\}^n}|x
angle_X$$
  $|0^m
angle_Y$ 

$$rac{1}{\sqrt{2^n}}\sum_{x\in\{0,1\}^n}|x
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angle_Y$$

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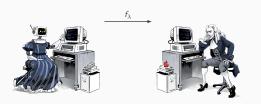
**Equation case**:  $d, d \cdot (x_0 \oplus x_1) = 0$ 

Assume there is a poly-time classical prover that succeeds in the protocol.

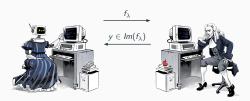




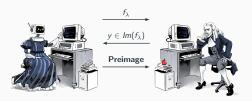
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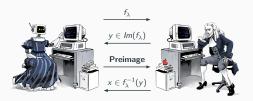
1. Send  $f_{\lambda}$ 



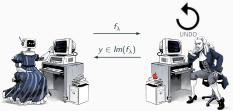
- 1. Send  $f_{\lambda}$
- 2. Ask for image



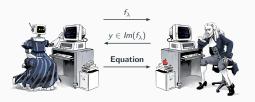
- 1. Send  $f_{\lambda}$
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- 3. Ask for preimage



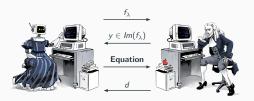
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- 2. Ask for image
- 3. Ask for preimage
- 4. Rewind

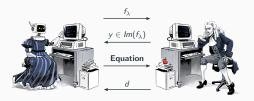


- 1. Send  $f_{\lambda}$
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- 4. Rewind
- 5. Ask for equation



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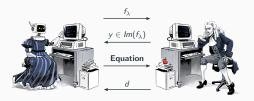
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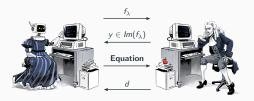


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BCMVV'18 proof of quantumness BCMVV'18 is a 4-message PoQ with  $c(\lambda) = 1$  and  $s(\lambda) = 3/4 + negl(\lambda)$ .

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Is the adaptive hardcore bit *necessary*? Can we base PoQs on just TCFs?

Yes! By "forcing" an equation onto the prover<sup>3</sup>.

<sup>&</sup>lt;sup>3</sup>[Kahanamoku-Meyer, Choi, Vazirani, Yao, 2021]



 $f_{\lambda}$  $y \in Im(f_{\lambda})$ 





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 $\frac{1}{\sqrt{2}}(|x_0\rangle+|x_1\rangle)$ 



 $f_{\lambda}$  $y \in Im(f_{\lambda})$ Preimage  $x \in f_{\lambda}^{-1}(y)$ 



 $\frac{1}{\sqrt{2}}(|x_0\rangle+|x_1\rangle)$ 





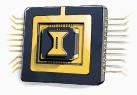


 $r \leftarrow_U \{0,1\}^{\operatorname{poly}(\lambda)}$ 

 $\frac{1}{\sqrt{2}}(|x_0
angle+|x_1
angle)$ 

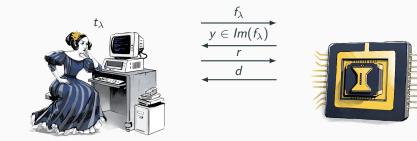






 $r \leftarrow_U \{0,1\}^{\operatorname{poly}(\lambda)}$ 

 $\frac{1}{\sqrt{2}}(|x_0\rangle + |x_1\rangle)$  $\frac{1}{\sqrt{2}}(|\mathbf{r} \cdot \mathbf{x}_0\rangle |x_0\rangle + |\mathbf{r} \cdot \mathbf{x}_1\rangle |x_1\rangle)$ 



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Hadamard and measure second register



$$\begin{array}{c}
f_{\lambda} \\
y \in Im(f_{\lambda}) \\
\hline
r \\
d
\end{array}$$



 $r \leftarrow_U \{0,1\}^{\operatorname{poly}(\lambda)}$ 

 $\begin{aligned} \frac{1}{\sqrt{2}}(|x_0\rangle + |x_1\rangle) \\ \frac{1}{\sqrt{2}}(|\boldsymbol{r} \cdot \boldsymbol{x}_0\rangle |x_0\rangle + |\boldsymbol{r} \cdot \boldsymbol{x}_1\rangle |x_1\rangle) \\ \frac{1}{\sqrt{2}}(|\boldsymbol{r} \cdot \boldsymbol{x}_0\rangle + (-1)^{d \cdot (x_0 \oplus x_1)} |\boldsymbol{r} \cdot \boldsymbol{x}_1\rangle) \end{aligned}$ 



$$\begin{array}{c} f_{\lambda} \\ \hline y \in Im(f_{\lambda}) \\ \hline r \\ \hline d \\ \hline m \\ \hline \end{array}$$



$$r \leftarrow_U \{0,1\}^{\operatorname{poly}(\lambda)}$$
$$m \leftarrow_U \{-\pi/4,\pi/4\}$$

 $\begin{aligned} \frac{1}{\sqrt{2}}(|x_0\rangle + |x_1\rangle) \\ \frac{1}{\sqrt{2}}(|\boldsymbol{r} \cdot \boldsymbol{x}_0\rangle |x_0\rangle + |\boldsymbol{r} \cdot \boldsymbol{x}_1\rangle |x_1\rangle) \\ \frac{1}{\sqrt{2}}(|\boldsymbol{r} \cdot \boldsymbol{x}_0\rangle + (-1)^{d \cdot (x_0 \oplus x_1)} |\boldsymbol{r} \cdot \boldsymbol{x}_1\rangle) \end{aligned}$ 



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$$\begin{array}{c} r \leftarrow_{U} \{0,1\}^{\mathrm{poly}(\lambda)} \\ m \leftarrow_{U} \{-\pi/4,\pi/4\} \\ \left\{ \begin{array}{c} \cos\left(\frac{m}{2}\right)|0\rangle + & \sin\left(\frac{m}{2}\right)|1\rangle \\ \cos\left(\frac{m}{2}\right)|1\rangle - & \sin\left(\frac{m}{2}\right)|0\rangle \end{array} \right\} \end{array}$$

$$\begin{split} & \frac{1}{\sqrt{2}}(|x_0\rangle + |x_1\rangle) \\ & \frac{1}{\sqrt{2}}(|\boldsymbol{r} \cdot \boldsymbol{x}_0\rangle |x_0\rangle + |\boldsymbol{r} \cdot \boldsymbol{x}_1\rangle |x_1\rangle) \\ & \frac{1}{\sqrt{2}}(|\boldsymbol{r} \cdot \boldsymbol{x}_0\rangle + (-1)^{d \cdot (x_0 \oplus x_1)} |\boldsymbol{r} \cdot \boldsymbol{x}_1\rangle) \end{split}$$



$$\begin{array}{c} f_{\lambda} \\ \hline y \in Im(f_{\lambda}) \\ \hline r \\ \hline d \\ \hline m \\ \hline o \end{array}$$



$$\begin{array}{c} r \leftarrow_{U} \{0,1\}^{\mathrm{poly}(\lambda)} \\ m \leftarrow_{U} \{-\pi/4,\pi/4\} \\ \left\{ \begin{array}{c} \cos\left(\frac{m}{2}\right)|0\rangle + & \sin\left(\frac{m}{2}\right)|1\rangle \\ \cos\left(\frac{m}{2}\right)|1\rangle - & \sin\left(\frac{m}{2}\right)|0\rangle \end{array} \right\} \end{array}$$

$$\frac{1}{\sqrt{2}}(|x_0\rangle + |x_1\rangle)$$

$$\frac{1}{\sqrt{2}}(|\mathbf{r} \cdot \mathbf{x}_0\rangle |x_0\rangle + |\mathbf{r} \cdot \mathbf{x}_1\rangle |x_1\rangle)$$

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Measure in basis *m* outcome *o*



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Use  $t_{\lambda}$ , r, d to compute *likely* o. Accept if prover sends likely o.

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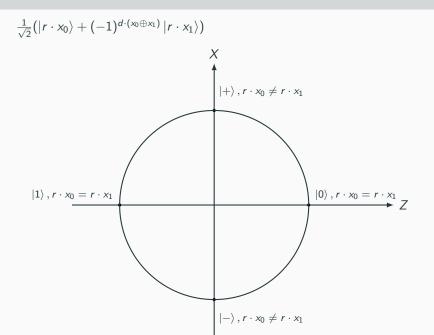
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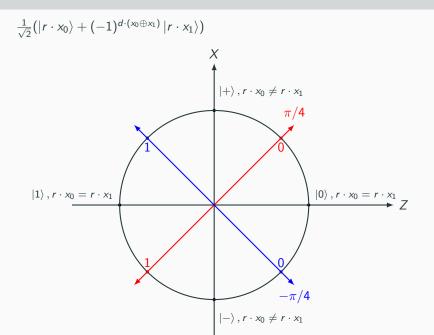
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Quantum prover succeeds with probability  $cos^2(\pi/8) \approx 85\%$ 



11



11

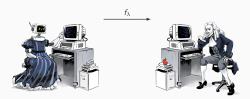
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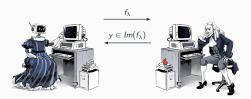


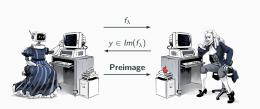
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1. Send  $f_{\lambda}$ 

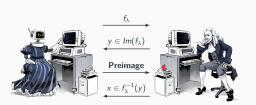


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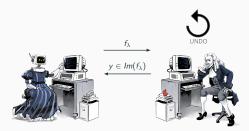




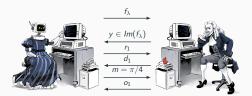
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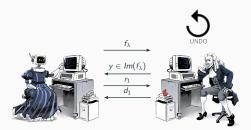
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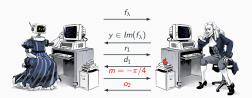
- 1. Send  $f_{\lambda}$
- 2. Ask for image
- 3. Ask for preimage
- 4. Rewind



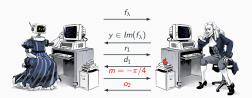
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- 4. Rewind
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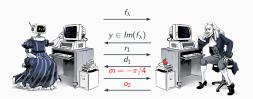


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- 6. Rewind
- 7. Do Bell test with  $r_1$ ,  $m = -\pi/4$ .



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- 4. Rewind
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- 7. Do Bell test with  $r_1$ ,  $m = -\pi/4$ . Repeat with  $r_2, r_3, ...$

Assume there is a poly-time classical prover that succeeds in the protocol. Use it to construct poly-time algorithm that breaks TCF claw-freeness.

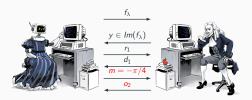


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Repeat with  $r_2, r_3, \ldots$ 

Outcomes  $o_1, o_2, ...$  determine bits of  $x_0 \oplus x_1$ .

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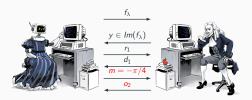
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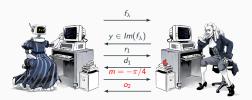
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Can recover both preimages, which contradicts claw-freeness!

Assume there is a poly-time classical prover that succeeds in the protocol. Use it to construct poly-time algorithm that breaks TCF claw-freeness.



- 1. Send  $f_{\lambda}$
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- 3. Ask for preimage
- 4. Rewind
- 5. Do Bell test with  $r_1$ ,  $m = \pi/4$ .
- 6. Rewind
- 7. Do Bell test with  $r_1$ ,  $m = -\pi/4$ .

Repeat with  $r_2, r_3, \dots$ 

#### KCVY'21 proof of quantumness

KCVY'21 is a 6-message PoQ with  $c(\lambda) = \frac{1}{2}(1 + \cos^2(\pi/8))$  and  $s(\lambda) = \frac{1}{2}(1 + 3/4) + \operatorname{negl}(\lambda)$ .

Brakerski, Porat and Vidick showed that preimage test can be removed!

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There's another way to do this with a simple modification...

#### KCVY'21 removing the preimage test



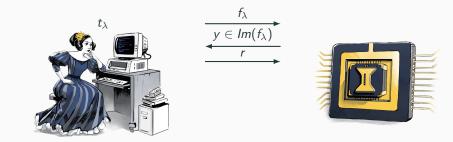
$$f_{\lambda}$$

$$y \in Im(f_{\lambda})$$



 $\frac{1}{\sqrt{2}}(|x_0
angle+|x_1
angle)$ 

<sup>&</sup>lt;sup>3</sup>[Gheorghiu, Kahanamoku-Meyer]



$$\frac{1}{\sqrt{2}}(|x_0,00..0\rangle + |00..0,x_1\rangle)$$

<sup>&</sup>lt;sup>3</sup>[Gheorghiu, Kahanamoku-Meyer]



 $r \leftarrow_U \{0,1\}^{2\text{poly}(\lambda)}$  $m \leftarrow_U \{-\pi/4,\pi/4\}$ 

Use  $t_{\lambda}$ , r, d to compute *likely o*. Accept if prover sends likely o.

$$egin{aligned} &rac{1}{\sqrt{2}}(|x_0,00..0
angle+|00..0,x_1
angle)\ &rac{1}{\sqrt{2}}(|r\cdot(x_0,00..0)
angle+\ &(-1)^{d\cdot(x_0\oplus x_1)}|r\cdot(00..0,x_1)
angle) \end{aligned}$$

Measure in basis *m*, outcome *o* 

<sup>&</sup>lt;sup>3</sup>[Gheorghiu, Kahanamoku-Meyer]



$$\begin{array}{c}
 f_{\lambda} \\
 y \in Im(f_{\lambda}) \\
 \hline
 r \\
 \hline
 d \\
 \hline
 m \\
 o \\
 \end{array}$$



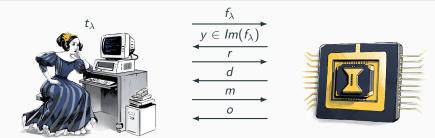
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angle) \end{aligned}$ 

Measure in basis m, outcome o

Hardcore bit is now  $r \cdot (x_0 || x_1)$ .

<sup>&</sup>lt;sup>3</sup>[Gheorghiu, Kahanamoku-Meyer]



 $r \leftarrow_U \{0,1\}^{2\mathrm{poly}(\lambda)}$  $m \leftarrow_U \{-\pi/4,\pi/4\}$ 

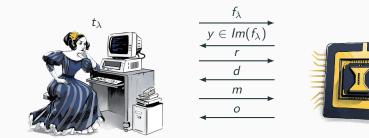
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angle) \end{aligned}$ 

Measure in basis m, outcome o

Hardcore bit is now  $r \cdot (x_0 || x_1)$ .

When doing the decoding in the soundness analysis, recover  $x_0||x_1$ .

<sup>&</sup>lt;sup>3</sup>[Gheorghiu, Kahanamoku-Meyer]



$$\leftarrow_U \{0,1\}^{2\mathrm{poly}(\lambda)}$$
  
$$n \leftarrow_U \{-\pi/4,\pi/4\}$$

r n

Use  $t_{\lambda}$ , r, d to compute *likely* o. Accept if prover sends likely o.  $egin{aligned} &rac{1}{\sqrt{2}}(|x_0,00..0
angle+|00..0,x_1
angle)\ &rac{1}{\sqrt{2}}(|r\cdot(x_0,00..0)
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angle) \end{aligned}$ 

Measure in basis m, outcome o

#### Preimageless KCVY'21 proof of quantumness

6-message PoQ with  $c(\lambda) = cos^2(\pi/8)$  and  $s(\lambda) = 3/4 + negl(\lambda)$ .

<sup>3</sup>[Gheorghiu, Kahanamoku-Meyer], [Brakerski, Porat, Vidick]

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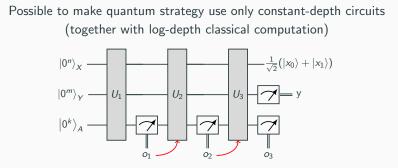
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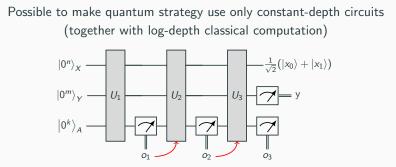
Potential for performing PoQs with non-fault tolerant quantum devices<sup>4</sup>...

<sup>4</sup>Interactive Protocols for Classically-Verifiable Quantum Advantage, Zhu et al. '22.

Possible to make quantum strategy use only constant-depth circuits (together with log-depth classical computation)



16



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Circuit width becomes quite high  $O(\lambda^8 \log(\lambda))$ .

## Non-interactive PoQs

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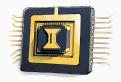
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$$\overbrace{(y,d,b)}^{f_{\lambda}}$$

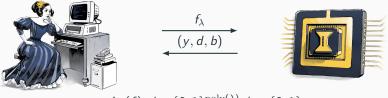


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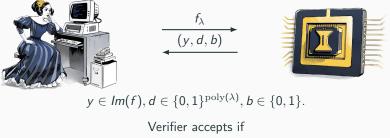
 $y \in Im(f), d \in \{0,1\}^{\mathrm{poly}(\lambda)}, b \in \{0,1\}.$ 

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BKVV'20 construction only relies on claw-freeness for soundness! Protocol can use TCFs, rather than STCFs.

## Non-interactive PoQs - YZ'22

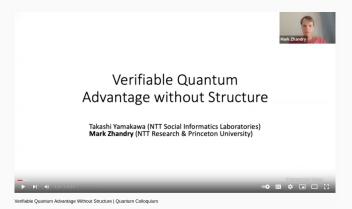
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#### Codeword-finding Problem (CFP)

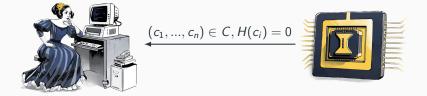
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Are there other PoQs that do not rely on TCFs?

Non-local games can be turned into proofs of quantumness<sup>7</sup>.

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If non-local game has quantum completeness c and classical soundness s, PoQ will have  $c(\lambda) = c$ ,  $s(\lambda) = s + negl(\lambda)$ .

<sup>&</sup>lt;sup>7</sup>[Kalai, Lombardi, Vaikuntanathan, Yang, 2022]

<sup>&</sup>lt;sup>8</sup>[Mahadev, 2018], [Brakerski, 2018]

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# Observations about KLVY'22

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- KCVY 6 messages, TCF, no preimage test.
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- YZ 1 (or 2) message(s), random oracle, publicly verifiable.
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#### Thanks!

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